DHV TESTREPORT EN926-2:2005

<u>Inflation/take-off</u>

Symmetric front collapse

ICARO WILDCAT M

Type designation ICARO WildCat M Type test reference no DHV GS-01-1877-10

Holder of certification ICARO paragliders - Fly & more GmbH Manufacturer ICARO paragliders - Fly & more GmbH

> **Classification** B Winch towing Yes

Number of seats min / max 1/1

Accelerator Yes Trimmers No



BEHAVIOUR AT MAX WEIGHT IN FLIGHT (110KG)

BEHAVIOUR AT MIN WEIGHT IN FLIGHT (80KG)

Test pilots



Beni Stocker

Rising behaviour Smooth, easy and constant rising

Harry Buntz

Smooth, easy and constant rising

<u>Landing</u> A

Special take off technique required No

Special landing technique required No

Speeds in straight flight A Trim speed more than 30 km/h Yes Yes

Speed range using the controls larger than 10 km/h Yes Yes

> Minimum speed Less than 25 km/h Less than 25 km/h

Control movement

Symmetric control pressure Increasing Symmetric control travel Greater than 60 cm Greater than 65 cm

Pitch stability exiting accelerated flight A

Dive forward angle on exit Dive forward less than 30° Dive forward less than 30° Collapse occurs No

Pitch stability operating controls during accelerated A Α

Collapse occurs No Nο

Roll stability and damping A

Oscillations Reducing Reducing

Stability in gentle spirals

Tendency to return to straight flight Spontaneous exit Spontaneous exit

Behaviour in a steeply banked turn (1) Sink rate after two turns 12 m/s to 14 m/s

12 m/s to 14 m/s

Entry Rocking back less than 45° Rocking back less than 45°

Recovery Spontaneous in less than 3 s Spontaneous in less than 3 s **Dive forward angle on exit** Dive forward 0° to 30° Dive forward 0° to 30°

Change of course Cascade occurs		Keeping course No
Cascade occurs	. 110	110
Symmetric front collapse in accelerated flight	В	В
Entry	Rocking back less than 45°	Rocking back less than 45°
-	Spontaneous in 3 s to 5 s	Spontaneous in 3 s to 5 s
Dive forward angle on exit	•	Dive forward 0° to 30°
Change of course		Keeping course
Cascade occurs		No
Exiting deep stall (parachutal stall)	A	A
Deep stall achieved	Yes	Yes
Recovery	Spontaneous in less than 3 s	Spontaneous in less than 3 s
Dive forward angle on exit	Dive forward 0° to 30°	Dive forward 0° to 30°
Change of course	Changing course less than 45°	Changing course less than 45°
Cascade occurs	s No	No
High angle of attack recovery	A	A
		•
Recovery Cascade occurs	Spontaneous in less than 3 s	Spontaneous in less than 3 s No
Recovery from a developed full stall	В	В
Dive forward angle on exit	: Dive forward 30° to 60°	Dive forward 30° to 60°
_	No collapse	No collapse
Cascade occurs (other than collapses)	No	No
Rocking back	Less than 45°	Less than 45°
Line tension	Most lines tight	Most lines tight
Asymmetric collapse 45-50%	A	A
		i e
Change of course until re-inflation		Less than 90°
Maximum dive forward or roll angle		Dive or roll angle 15° to 45°
Total change of course	Spontaneous re-inflation	Spontaneous re-inflation Less than 360°
Collapse on the opposite side occurs		No
Twist occurs		No
Cascade occurs		No
Asymmetric collapse 70-75%	В	¦B
Change of course until re-inflation	90° to 180°	90° to 180°
Maximum dive forward or roll angle	_	Dive or roll angle 15° to 45°
Re-inflation behaviour	· Spontaneous re-inflation	Spontaneous re-inflation
Total change of course	Less than 360°	Less than 360°
Collapse on the opposite side occurs		No
Twist occurs		No
Cascade occurs	SINO	No
Asymmetric collapse 45-50% in accelerated flight	A	A
Change of course until re-inflation	Less than 90°	Less than 90°
Maximum dive forward or roll angle		Dive or roll angle 15° to 45°
_	Spontaneous re-inflation	Spontaneous re-inflation
Total change of course	•	Less than 360°
Collapse on the opposite side occurs		No
Twist occurs		No
Cascade occurs	: No	No
A		in
	В	¦B
Change of course until re-inflation		90° to 180°
Maximum dive forward or roll angle	_	Dive or roll angle 15° to 45°
	Spontaneous re-inflation	Spontaneous re-inflation
Total change of course		Less than 360°
Collapse on the opposite side occurs		No
Twist occurs		No No
Cascade occurs	5 NO	No
Directional control with a maintained asymmetric	A	
collapse	.A	¦ A
Able to keep course		Yes
1000 tires arrain from the colleged alde secolble in	Voc	Vac

Vac

1000 turn sursufuem the colleged side massible in Vac

res

Yes

Nο

More than 50 % of the symmetric control travel

spin travel Trim speed spin tendency Α Spin occurs No Nο Α Low speed spin tendency Spin occurs No Nο Recovery from a developed spin A Α **Spin rotation angle after release** Stops spinning in less than 90° Stops spinning in less than 90° Cascade occurs No No **B-line stall** Α Change of course before release Changing course less than 45° Changing course less than 45° Behaviour before release Remains stable with straight span Remains stable with straight span **Recovery** Spontaneous in less than 3 s Spontaneous in less than 3 s Dive forward angle on exit Dive forward 0° to 30° Dive forward 0° to 30° Cascade occurs No Α Big ears Entry procedure Dedicated controls Dedicated controls Behaviour during big ears Stable flight Stable flight **Recovery** Spontaneous in less than 3 s Spontaneous in less than 3 s Dive forward 0° to 30° Dive forward angle on exit Dive forward 0° to 30° Big ears in accelerated flight **Entry procedure** Dedicated controls Dedicated controls Behaviour during big ears Stable flight Stable flight **Recovery** Spontaneous in less than 3 s Spontaneous in less than 3 s Dive forward angle on exit Dive forward 0° to 30° Dive forward 0° to 30° Behaviour immediately after releasing the Stable flight Stable flight accelerator while maintaining big ears Behaviour exiting a steep spiral Tendency to return to straight flight Spontaneous exit Spontaneous exit Turn angle to recover normal flight Less than 720°, spontaneous recovery Less than 720°, spontaneous recovery Sink rate when evaluating spiral stability [m/s] 14 Alternative means of directional control Α

Any other flight procedure and/or configuration described in the user's manual

180° turn achievable in 20 s Yes

Stall or spin occurs No

No other flight procedure or configuration described in the user's manual

by jursaconsulting